

EGU General Assembly Vienna 2014 Stream-potential formulation of atmospheric dynamics in pressure coordinates University of Tartu, Estonia R. Rõõm

Supported by Estonian Science Foundation Grant 9134

Abstract

Departing from covariant presentation of non-hydrostatic atmospheric dynamics in isobaric coordinates [R. Rõõm 1990: General form of non-hydrostatic equations of atmospheric dynamics in isobaric coordinates. Atm. Ocean Physics. v. 26, 17 26. [http://meteo.physic.ut.ee/room/papers/kuni2004/1990.General_Form.pdf] equations of 4-dimensional stream-potential dynamics are derived.

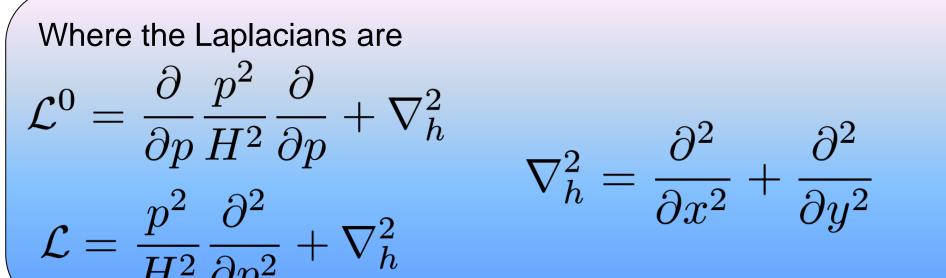
1. Vectors and tensors in pressure coordinates

While passing from ordinary coordinates x,y,z,t to the pressurecoordinate frame x,y,p(x,y,z,t),t, a vector with components V^{X}, V^{Y}, V^{Z} , in orthogonal vector basis i_x , i_y , i_z will have in p(ressure)-space contravariant components V^X, V^Y, V^p in covariant basis e_x, e_y, e_p and covariant components $v_{x'}v_{y'}v_p$ in contravariant basis $\mathbf{e}_{x}, \mathbf{e}_{y}, \mathbf{e}_{p}$



$\mathbf{v} - \mathbf{I}_{\alpha} \underline{v} - \mathbf{e}_{\alpha} v - \mathbf{e}_{\alpha} v_{\alpha}$	
$\frac{\mathbf{a} \cdot \mathbf{e}^{\mathbf{x}}}{\mathbf{a} \cdot \mathbf{e}^{\mathbf{x}}}$ In particular, if V is the velocity of a material particle then $\frac{v^{x}}{\mathbf{a} \cdot \mathbf{e}^{\mathbf{x}}}$ $\frac{v^{x}}{\mathbf{a} \cdot \mathbf{e}^{\mathbf{x}}} = \frac{dx}{dt}, v^{x} = \frac{dx}{dt}$ $\frac{v^{y}}{\mathbf{a} \cdot \mathbf{e}^{\mathbf{y}}} = \frac{dy}{dt}, v^{y} = \frac{dy}{dt}$ $\frac{v^{z}}{\mathbf{e}^{\mathbf{p}}} = \frac{dz}{dt}, v^{p} = \frac{dp}{dt} = c$	dtlt
Properties of curvilinear p(pressure)-space are specified with the metric tensor with $H = RT/g$ $G^{\alpha\beta} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & p^2/H \end{bmatrix}$	2 For verify and a for a
The most important geometrical objects in p-space are the geopotential height gradient, velocity divergence and forticity (velocity curl) $\xi^{j} = (\mathbf{\nabla} \times \mathbf{v})^{j} = -\frac{p}{H} \varepsilon^{j\alpha\beta} \partial_{\alpha} v_{\beta}, \ v_{\beta} = G_{\beta\gamma} v_{\beta}$.,γ.
2. Velocity 4-potential $\{\psi^{0}, \psi\} = \{\psi^{0}, \psi^{x}, \psi^{y}, \psi^{p}\}$ Velocity can be presented as the sum of scalar-potential gradient and vector-potential curl : $v^{j} = G^{j\alpha} \partial_{\alpha} \psi^{0} + \varepsilon^{j\alpha\beta} \partial_{\alpha} \psi_{\beta}$ (1)	}
P Compressible securitie	Р
Compressible acoustic oscillation	

 $\mathcal{L}^{0}\psi^{0} = \xi^{0} \qquad \mathcal{L}\psi^{p} = -\frac{p^{2}}{H^{2}}\xi^{p}$ $\mathcal{L}\omega = \frac{p^{2}}{H^{2}}\left(\partial_{y}\xi^{x} - \partial_{x}\xi^{y}\right)$ $\nabla_h^2 \psi_x = -\partial_x \partial_p \psi^p - \partial_y \omega$ $\nabla_h^2 \psi_y = \partial_x \omega - \partial_y \partial_p \psi^p$



for use of these elliptic equations, with sources expressed in terms of elocity divergence and curl, volutional equations for 4-vector $\{\xi^0, \ \boldsymbol{\xi}\} = \{\xi^0, \xi^x, \xi^y, \xi^p\}$ re required.

$$\begin{aligned} \frac{\partial \mathbf{v}}{\partial t} &= -\mathbf{\Xi} \times \mathbf{v} - \mathbf{\nabla} (gz + \mathbf{v} \cdot \mathbf{v}/2) - \mathbf{F} \\ \mathbf{\Xi} &= \mathbf{i}_z f + \boldsymbol{\xi} \qquad (\mathbf{\Xi} \times \mathbf{v})^j = -\varepsilon^{j\alpha\beta} \Xi_\alpha v_\beta \\ \mathbf{F} &: F^x = 0, \ F^y = 0, \ F^p = \omega \partial_t \ln H \end{aligned}$$

